
Weighted Compressed Sensing and Rank Minimization



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Prague



Outline

- ▶ Compressed Sensing with Prior Info
- ▶ Related Work
- ▶ Problem Definition
- ▶ Contributions
 - ▶ A simple and explicit rule for weighted – CS
 - ▶ Analysis works for **arbitrary** number of partitions
 - ▶ A proposal for weighted RM
- ▶ Technical Details

Compressed Sensing

- ▶ Typical compressed sensing setup:

- ▶ $x_0 \in \mathbb{R}^n$ is a sparse vector, $A \in \mathbb{R}^{m \times n}$ is the measurement matrix and $y_0 = Ax_0 \in \mathbb{R}^m$ are the measurements.
- ▶ Aim is to recover x_0 in the case $m \ll n$.
- ▶ ℓ_1 – minimization:

$$\min \|x\|_1 \quad \text{subject to } Ax = y_0$$

- ▶ A great amount of work is dedicated to sparse recovery.
 - ▶ Fast algorithms
 - ▶ Signals with certain structure
 - ▶ Noise analysis

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 - ▶ Fast algorithms
 - ▶ **Signals with certain structure**
 - ▶ Noise analysis

Non-uniform sparsity

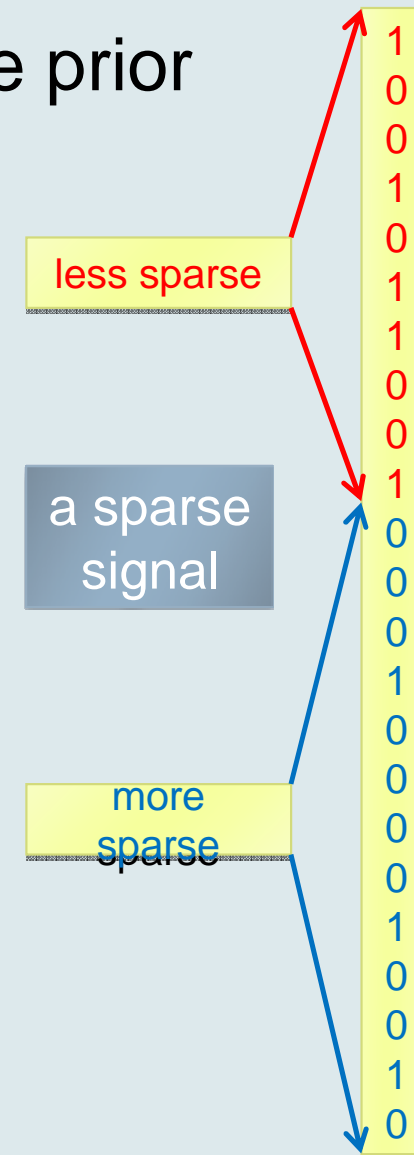
- ▶ In many applications, we have some prior knowledge on support of the signal.
 - ▶ Natural images
 - ▶ Biomedical images
 - ▶ Network monitoring data
 - ▶ DNA micro-arrays

a sparse signal

1
0
0
1
0
1
1
0
0
0
1
0
0
0
0
0
0
0
1
0
0
1
0
0

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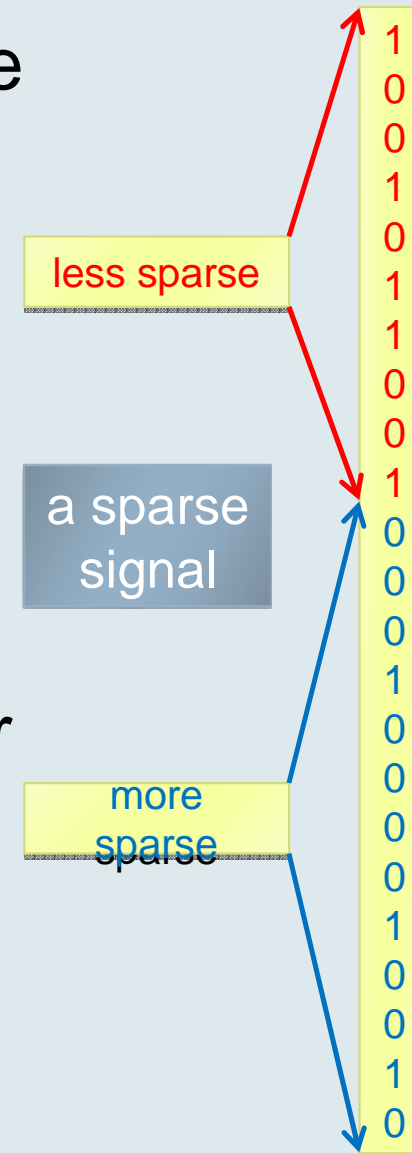
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- ▶ Modify the algorithm to account for

Algorithm: Assume $\{S_i\}_{i=1}^t$ partitions $\{1, 2, \dots, n\}$ into t disjoint sets. Then **weighted** ℓ_1 minimization is given by:

$$\min \sum_{i=1}^t w_i \|x_{S_i}\|_1 \quad \text{subject to } Ax = y_0$$



Problem Setting

- ▶ For each $i \leq t$, let fraction of **nonzero entries** on p_i be where $0 \leq p_i \leq 1$.
- ▶ We assume the knowledge of $\{p_i\}_{i=1}^t$ and $\{d_i\}_{i=1}^t$.
- ▶ Aim is to minimize number of measurements m while recovering x_0 w.h.p.

Main question: Given $\{p_i\}_{i=1}^t$ and $\{d_i\}_{i=1}^t$ how to choose the weights $\{w_i\}_{i=1}^t$ to be able to recover x_0 from fewest number of measurements?

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- ▶ Previously analyzed in a number of papers.
 - ▶ Vaswani and Lu, “Modified – CS: ...” (2010)
 - ▶ Khajejnejad et al. “Weighted ℓ_1 – minimization ...” (2009)

Our approach

- ▶ We assume Gaussian measurements.
 - ▶ Entries of $A \in \mathbb{R}^{m \times n}$ is i.i.d. Gaussian
- ▶ Analysis is performed via a new technique introduced by Recht et al. for RMP.
 - ▶ “Null space conditions and thresholds for RM” (2008)
- ▶ Unlike previous results, we are able to find a simple weighting rule for **arbitrary** number of partitions.
 - ▶ Our results suggest $w_i = 1 - p_i$
 - ▶ Consistent with “punish the sparser” intuition
 - ▶ An alternative to exhaustive search
- ▶ **Tradeoff:** Analysis is suboptimal.



Strategy

▶ **Main steps:**

1. Find the condition for recovery of x_0
2. Analyze the condition with the new framework
3. Find the optimal weights

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Lemma (Null Space Condition)

Let K be support set of x_0 . Then x_0 can be recovered via ℓ_1 weighted ℓ_1 if and only if for all z we have:

$$F(\mathbf{z}, \mathbf{w}) = \sum_{i=1}^t w_i \left(\sum_{j \in S_i \cap K} \text{sgn}(x_j) z_j + \sum_{l \in S_i \cap K^c} |z_l| \right) > 0$$

Strategy

► Main steps:

1. Find the condition for recovery of x_0
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 1. We need to make sure $F(\mathbf{z}, \mathbf{w})$ is positive for all \mathbf{z} .
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Theorem (Lower bounding $F(\mathbf{z}, \mathbf{w})$)

Let $\alpha_i = |S_i|/n$ for all $i \leq t$ and $\mu = m/n$. Then $F(\mathbf{z}, \mathbf{w})$ is positive for all $\mathbf{z} \in \mathcal{N}(\mathbf{A})$ if the following holds:

$$f(\mathbf{w}) = c_0 \sum_{i=1}^t w_i \alpha_i (1 - p_i) - ((1 - \mu) \sum_{i=1}^t w_i^2 \alpha_i)^{1/2} > 0$$

where $c_0 = \sqrt{2/\pi}$.

Proof idea

Theorem (Lower bounding $F(\mathbf{z}, \mathbf{w})$)

Let $\alpha_i = |S_i|/n$ for all $i \leq t$ and $\mu = m/n$. Then $F(\mathbf{z}, \mathbf{w})$ is positive for $\mathbf{z} \in N(\mathbf{A})$ if the following holds:

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where $c_0 = \sqrt{2/\pi}$.

- ▶ Proof is based on
 - ▶ Gordon's inequalities on Gaussian processes
 - ▶ "Some inequalities for Gaussian processes ..." (1985)
 - ▶ Concentration for Lipschitz functions of Gaussians

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In particular, we try to estimate

$$\mathbb{E} \left[\inf_{\|\mathbf{v}\|_2=1} \left\| \sum_{i=1}^p v_i \mathbf{g}_i \right\|_1 \right]$$

where $\{\mathbf{g}_i\}_{i=1}^p$ are i.i.d. Gaussian vectors which corresponds to a basis $\mathbf{N}(A)$.

Optimal weights

▶ Main steps:

1. Find the condition for recovery of x_0
2. Analyze the condition with the new framework
 1. We need to make sure $F(\mathbf{z}, \mathbf{w})$ is positive for all \mathbf{z} .
3. **Find the optimal weights**

Theorem (Optimal weights)

Given $\{p_i\}_{i=1}^t$ and $\{S_i\}_{i=1}^t$, in order to minimize ϵ while keeping $f(\mathbf{w})$ positive, we need to choose

$$w_i = 1 - p_i \quad \text{for all } i \leq t$$

- ▶ Interestingly, weighting rule does not depend $|S_i|$.

Reduction in measurements

- ▶ Our analysis provides a simple intuition on how weighting is useful.
 - ▶ Let $r = n - m$ denote the *dimensionality reduction*.

- ▶ For regular ℓ_1 – minimization

$$r_{reg} = c_0^2 \left(1 - \sum_i \alpha_i p_i\right)^2$$

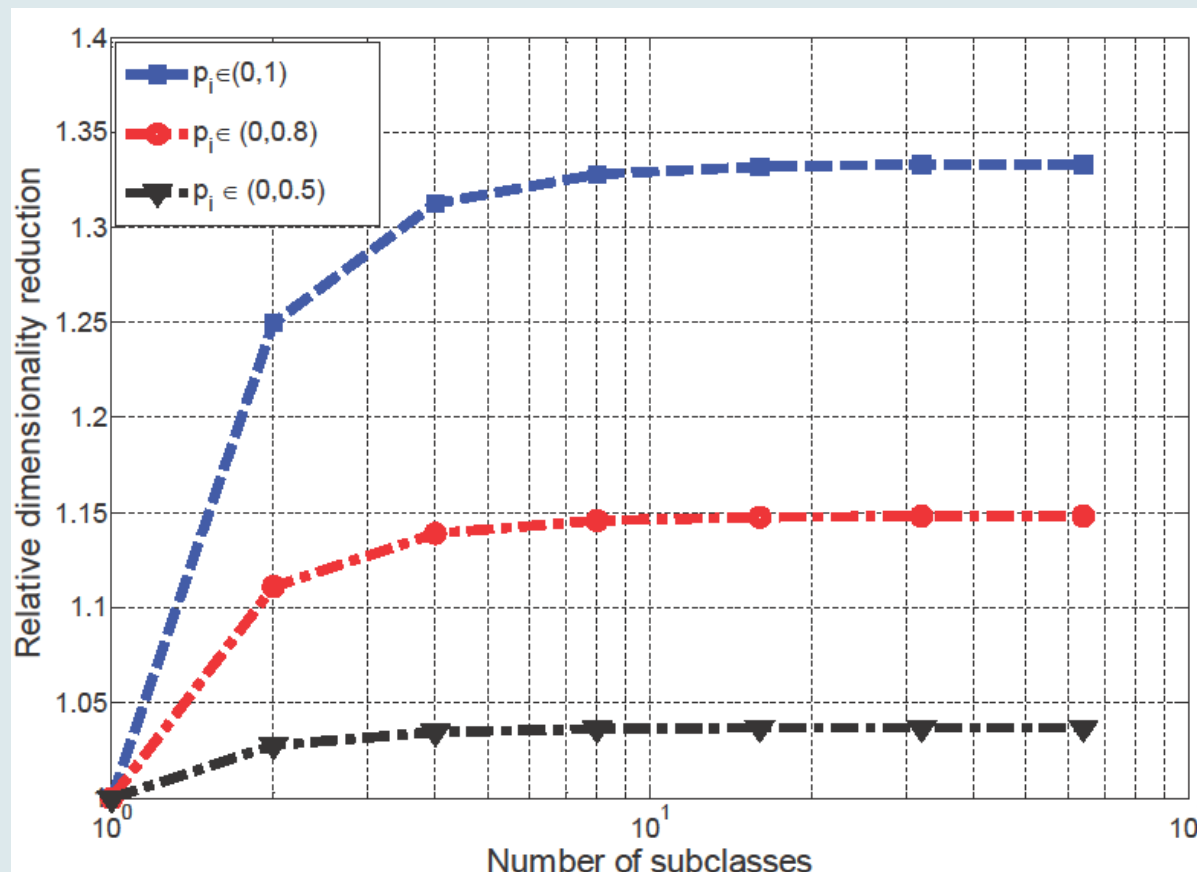
- ▶ For weighted ℓ_1 with $w_i = 1 - p_i$

$$r_{opt} = c_0^2 \sum_i (1 - p_i)^2 \alpha_i$$

- ▶ From convexity of x^2 we always have $r_{opt} \geq r_{reg}$

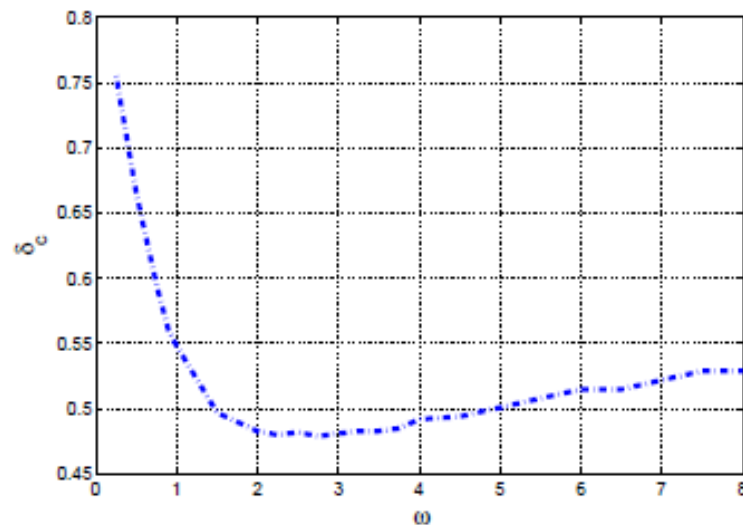
Dimensionality reduction

- ▶ Relative reduction in number of measurements (r_{opt} / r_{reg}) as we use more and more weighted sections.
 - ▶ Sparsity of partitions is uniformly spaced from 0 to 0.5, 0.8 or 1.

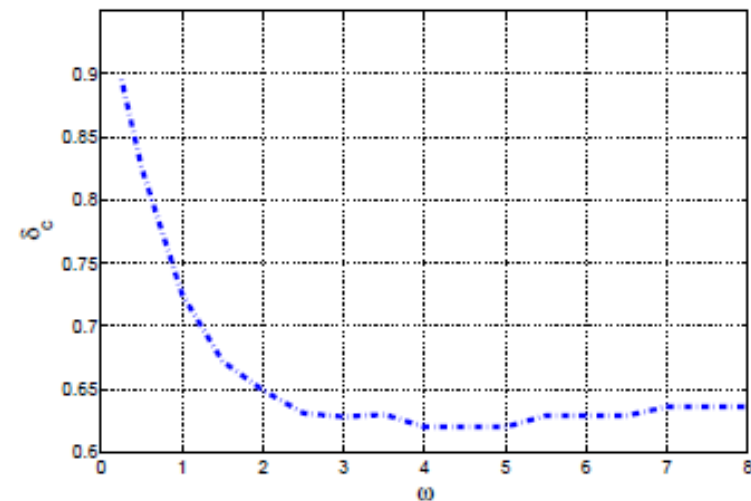


Comparison with previous work

- ▶ Khajehnejad et al. studied the optimal weighting for two partitions. Which w_1 is optimal?
- ▶ Problem becomes intractable as number of partitions increases



(a) $p_1 = 0.4, p_2 = 0.05$.

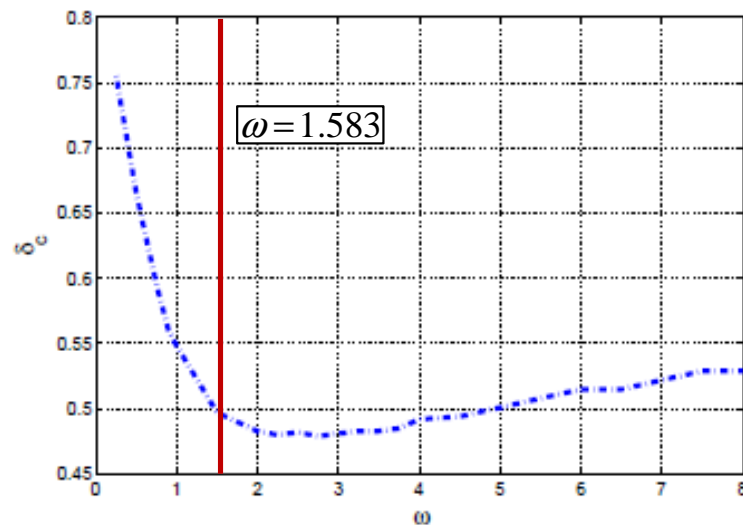


(b) $p_1 = 0.65, p_2 = 0.1$.

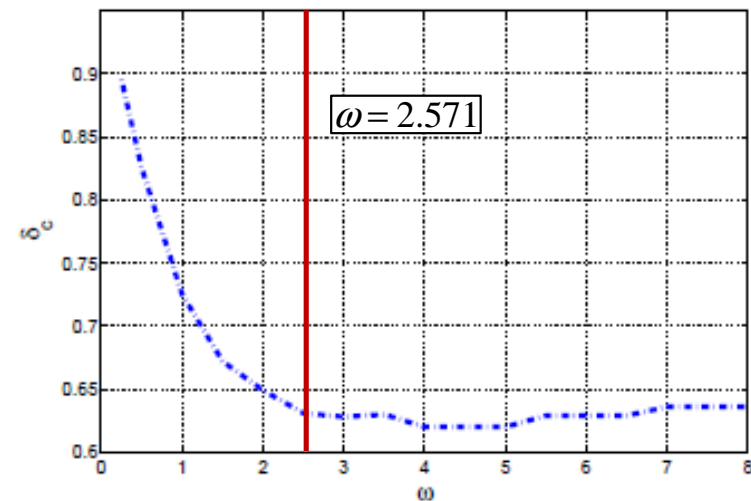
Figure 2: δ_c as a function of $\omega = \frac{w_{K2}}{w_{K1}}$ for $\gamma_1 = \gamma_2 = 0.5$.

Comparison with previous work

- ▶ Khajehnejad et al. studied the optimal weighting for two partitions. Which w_1 is optimal?
- ▶ Our prediction: $\omega = (1 - p_2) / (1 - p_1)$



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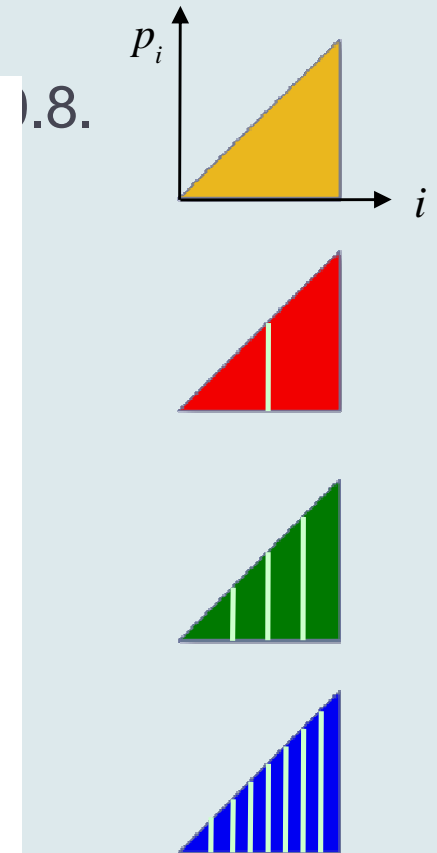
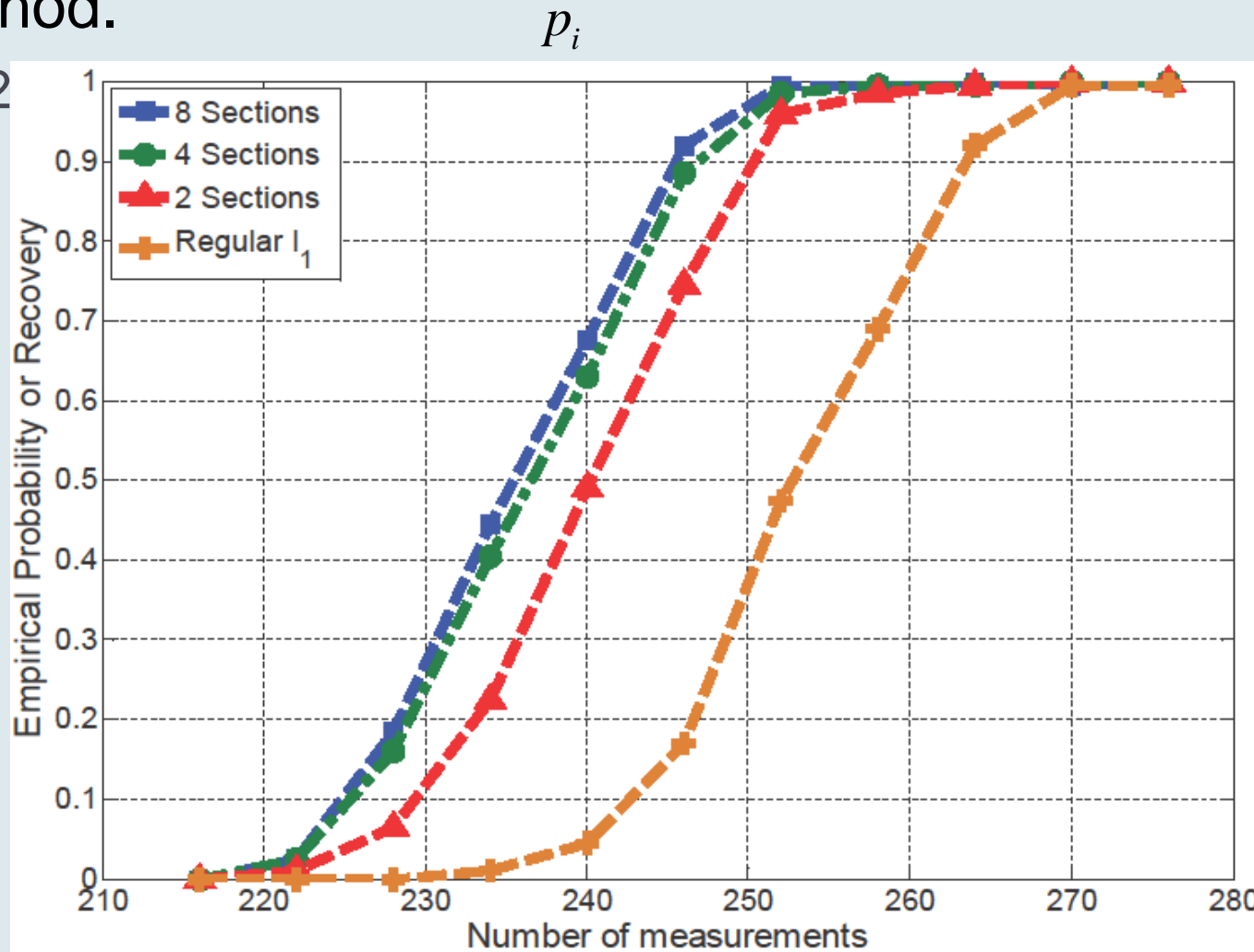
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Simulation results

- ▶ Empirical recovery curves for the proposed weighting method.

▶ 32



▶ 32

Extension to Rank Minimization

- ▶ Similar to support set of a sparse signal, singular vectors of low rank matrices are not necessarily uniformly distributed.
 - ▶ In images, generally most of the energy is concentrated in low frequencies.
 - ▶ Quantum tomography
 - ▶ Structured problems
- ▶ Some **subspaces** might be **sparser** than others.

Weighted RM

- ▶ We want to recover low rank $X_0 \in \mathbb{R}^{n_1 \times n_2}$ subject to measurements $y_0 = A(X_0)$.

Algorithm: Let $X_0 \in \mathbb{R}^{n_1 \times n_2}$ and $\{S_i\}_{i=1}^t$ be subspaces of \mathbb{R}^{n_1} orthogonal to each other with $S_i \oplus S_j = \mathbb{R}^{n_1}$. Then **weighted** NNM algorithm is given by

$$\min \| (w_1 U_1 \dots w_t U_t)^T X \|_1 \quad \text{subject to } A(X) = y_0$$

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Algorithm: Let $X_0 \in \mathbb{R}^{n_1 \times n_2}$ and $\{S_i\}_{i=1}^t$ be subspaces of \mathbb{R}^{n_1} orthogonal to each other with $S_i \perp S_j$ for $i \neq j$ and $\dim S_i = n_1$. Then **weighted** NNM algorithm is given by

$$\min \| (w_1 U_1 \dots w_t U_t)^T X \|_f \quad \text{subject to } A(X) = y_0$$

- ▶ Algorithm modifies regular **nuclear norm** $\min \| X \|_f$ subject to $A(X) = y_0$

Analysis

- ▶ Assume X_0 has $p_i \dim(S_i)$ singular vectors lying on S_i .
- ▶ Problem can be analyzed similarly.
 - ▶ Gaussian measurements
 - ▶ Exactly same technique
- ▶ Result is more convoluted. However when $n_1 / n_2 \rightarrow 0$ we $w_i = 1 - p_i$ as optimal weights: