Scheduling of CAL actor networks based on dynamic code analysis

Mickaël Raulet

INSA Rennes, France

Jani Boutellier, Olli Silvén

University of Oulu, Finland



Motivation

Jani Boutellier

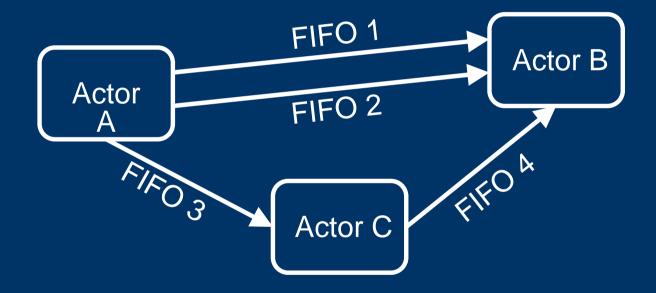
 Describing computer programs can be done at different levels of abstraction

	Assembly	С	RVC-CAL	Functional languages
<	low	level of abs	straction	high
	implementation efficiency			reusability analyzability verifiability productivity

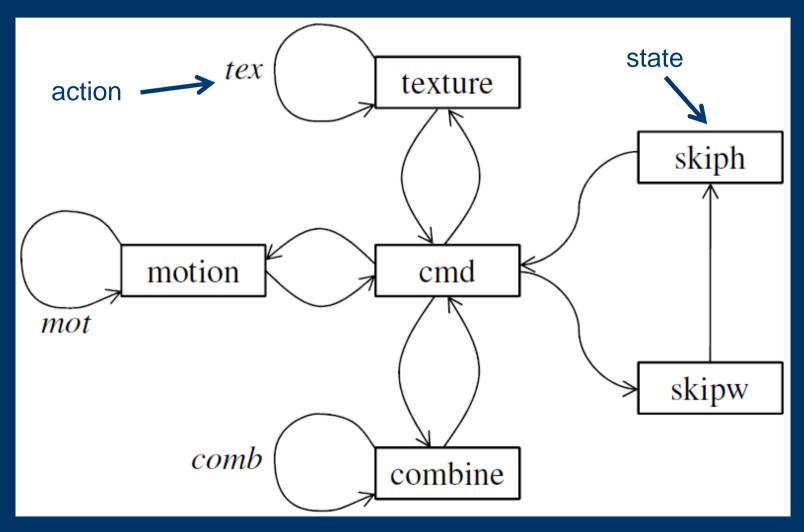
UNIVERSITY of

- A dataflow language that is a subset of the CAL language originally developed at UC Berkeley
- The RVC-CAL language has been standardized by ISO (ISO/IEC23001-4) in 2009











The main differences between the RVC-CAL and traditional dataflow models of computation:

- Allows conditional execution
- + Makes the language applicable to a wider set of applications
- Makes the language harder to analyze for humans and compilers



Topic of this work

The main point of our work is to improve the efficiency of programs written in RVC-CAL

Assembly C RVC-CAL

higher implementation efficiency lower



Method of this work

- In RVC-CAL, each dataflow actor runs completely independently
- Basically this is good, as it improves the modularity of the language
- In practice, the actors within a program are very dependent on each other's behaviour
- We try to automatically discover these interdependencies and optimize the implementation with this information



Method of this work

- Our approach is based on dynamic program analysis
- In dynamic analysis the behaviour of the program is examined as it is running
- Based on information acquired from analysis, a new, more efficient version of the program can be generated



- 1. Finding the data dependencies
- 2. Detecting the strands
- 3. Detecting the actor signatures
- 4. Code generation

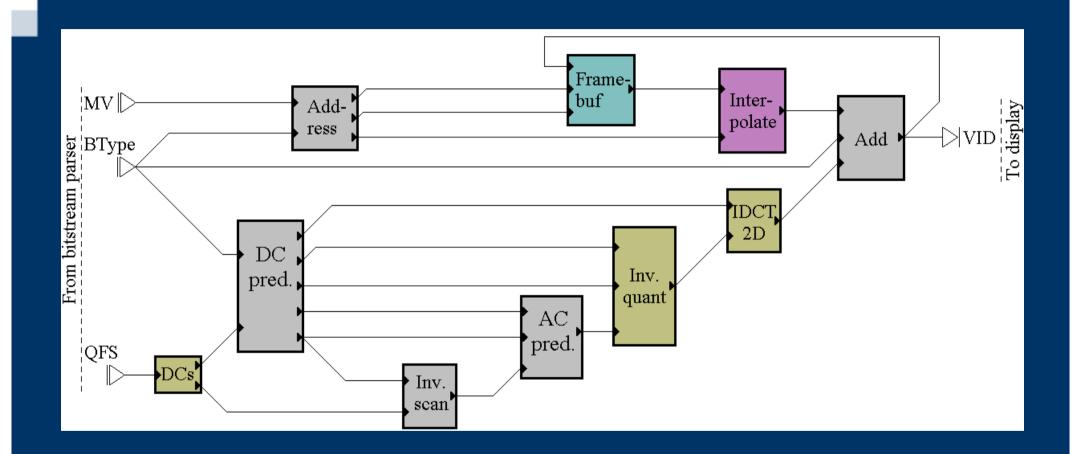


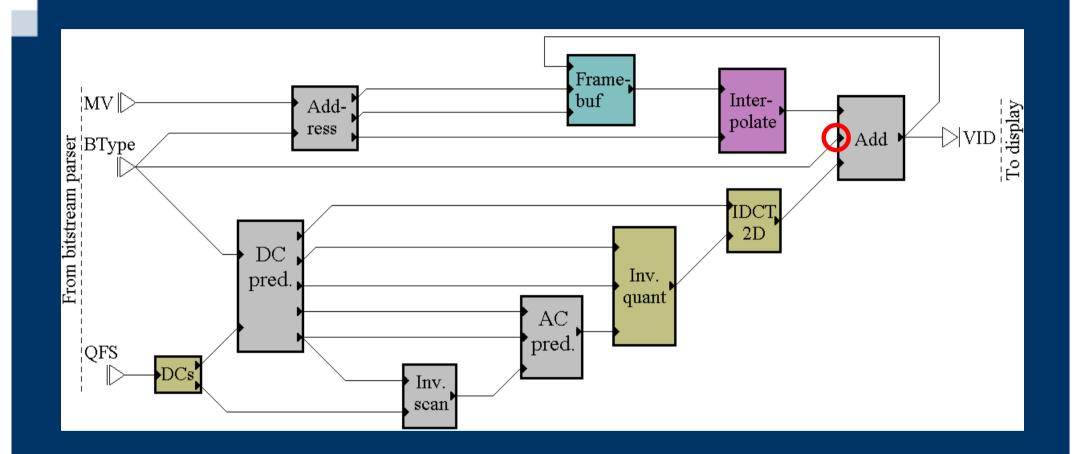
Finding the data dependencies

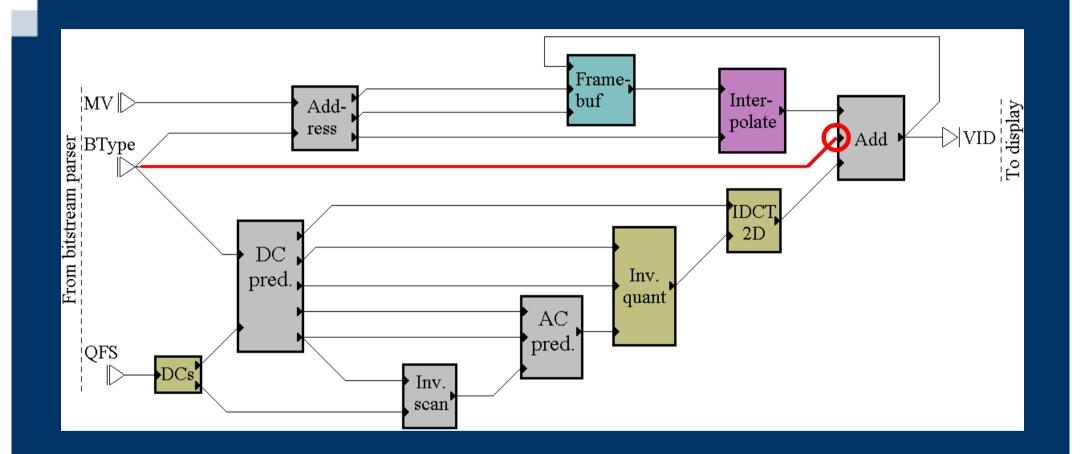
- The first step in our approach is to automatically find the signals in the network that cause conditional execution (control signals)
- The detection rule for these signals is

If the value of data incoming from FIFO *f* affects the behaviour of an actor, *f* is a control signal







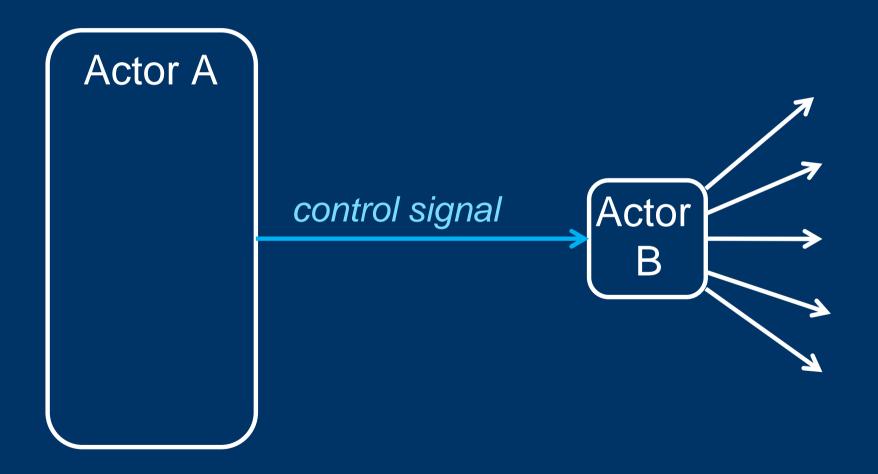


- 1. Finding the data dependencies
- 2. Detecting the strands
- 3. Detecting the actor signatures
- 4. Code generation

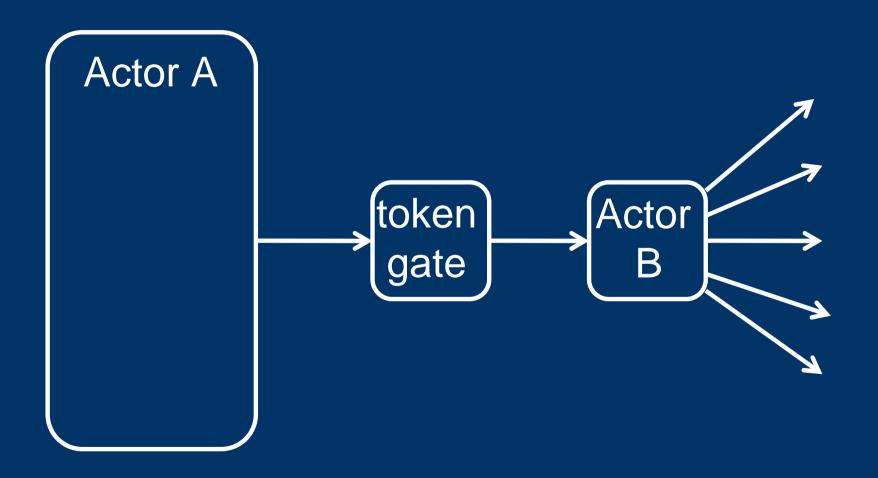


- Knowing the control signals in the actor network, we want to express the behaviour of the network as a function of the control signal tokens
- To be able to observe and control the network behaviour, we insert special actors named token gates to control signals









- A strand is a sequence of actor invocations.
 Each value coming through the token gate invokes 1 strand at run-time
- The strands can be detected automatically with the help of token gating:
- 1) Let a token throught the gate and observe its value
- 2) record the set of actors that it invokes



- However, this is not enough
- Generally, actors can behave in many different ways for each value passing through the token gate
- Therefore, we also need to find all the different actor behaviours for each strand



- 1. Finding the data dependencies
- 2. Detecting the strands
- 3. Detecting the actor signatures
- 4. Code generation



Detecting the actor signatures

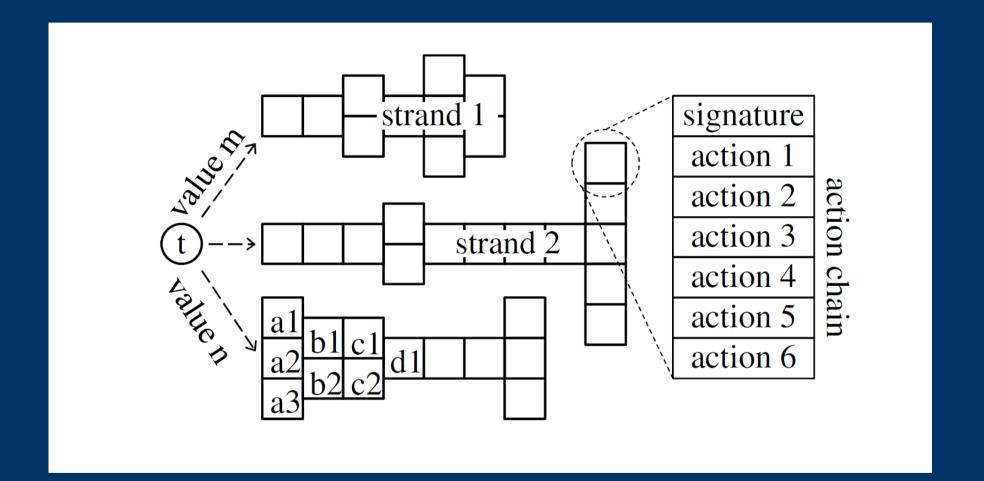
- The behaviour of a CAL actor can be fully predicted before its execution by looking at the following properties
 - 1. Values of state variables
 - 2. Number of tokens at input ports
 - 3. Value of tokens at input ports
- These form the signature of the actor



Detecting the actor signatures

- At the network analysis stage, the actor signatures are recorded before letting the actor execute
- For every signature, the sequence of executed actions is recorded





- 1. Finding the data dependencies
- 2. Detecting the strands
- 3. Detecting the actor signatures
- 4. Code generation



Code generation

- Now we have modeled the functionality of the application with gate token values and actor signatures
- Next, we generate the C code of a tokengated run-time program
- Make a switch-statement for each token gate value and signature



Results

MPEG-4 part 2 decoders

"MVG" 2.11x speedup

"RVC" 1.14x speedup

"Serial" 1.33x speedup

"Xilinx" 1.20x speedup



Conclusion

- We have presented a fully automated approach to speed up implementations of programs written in RVC-CAL
- The average speedup provided by our approach is 1.5x on the used set of RVC-CAL networks



Directions for future work

- Based on the lessons learned from the dynamic analysis approach, a static analysis approach could be developed
- Improving the code generation would provide better speedups
- Make the method applicable to programs with several data dependencies



Thanks for your attention.

Questions?

